

General Description

The MAX14483 is a 6-channel, 3.75kV_{RMS} digital galvanic isolator using Maxim's proprietary process technology. The six signal channels are individually optimized for SPI applications and include very low propagation delay on the SDI, SDO, and SCLK channels. The SDO channel's tri-state control is enabled by the \overline{CS} input as well as a second enable control input pin (\overline{SDOEN}), allowing a single MAX14483 to isolate multiple SPI devices. To simplify system design, an open-drain \overline{FAULT} output can be wire ORed with error outputs from other devices. In addition, an auxiliary channel (AUX) is available for passing timing or control signals from the master side to the slave side and power monitors (SAA, SBA) are provided for both power domains to signal if the opposite side of the isolator is ready for operation. Independent 1.71V to 5.5V supplies on each side of the isolator also make the device suitable for use as a level translator.

The MAX14483 has an isolation rating of 3.75kV_{RMS} for 60 seconds and is available in a 20-pin SSOP package with 5.5mm of creepage and clearance. The package material has a minimum comparative tracking index (CTI) of 400V, which gives it a group 2 rating in creepage tables.

The MAX14483 is rated for operation at ambient temperatures of -40°C to +125°C.

Applications

- Programmable Logic Controllers
- Industrial Automation
- Process Automation
- Building Automation
- Robotics
- General SPI-bus Isolation

Benefits and Features

- Saves Space and Components
 - 6 Isolated Channels in a 20-SSOP Package
- Low Propagation Delay on SCLK, SDI, and SDO
 - Up to 100MHz Clock, 200Mbps Data Rate
 - 10ns Typical Propagation Delay
 - 2ns Maximum Pulse Width Distortion
 - 250ps Typical Peak Jitter
- Robust Galvanic Isolation of Digital Signals
 - Withstands 3.75kV_{RMS} for 60s (V_{ISO})
 - Continuously Withstands 450V_{RMS} (V_{IOWM})
 - Withstands ± 10 kV Surge between GNDA and GNDB with 1.2/50 μ s Waveform
 - High CMTI (50kV/ μ s, Typical)
- Flexible System Design
 - Wide 1.71V to 5.5V Voltage Range on Each Side
 - \overline{SDOEN} Control Pin for Sharing Isolators
 - Open-Drain \overline{FAULT} Channel for Shared Interrupt on Master Side
 - Auxiliary Channel for Timing or Control
- Low Power Consumption
 - 1.53mW per Channel at SCLK = 10MHz with $V_{DD} = 3.3$ V
 - 0.77mW per Channel at SCLK = 10MHz with $V_{DD} = 1.8$ V

Safety Regulatory Approvals (Pending)

- UL According to UL1577
- cUL According to CSA Bulletin 5A

Ordering Information and Typical Operating Circuits appear at end of data sheet.

Absolute Maximum Ratings

| | |
|--|---|
| V _{DDA} to GNDA, V _{DDB} to GNDB |-0.3V to +6V |
| ICS, ISCLK, ISDI, IAUX, SDOEN, OFAULT | |
| to GNDB |-0.3V to +6V |
| OSDO, SAA to GNDB |-0.3V to (V _{DDB} + 0.3V) |
| ISDO, IFAULT, IRDY to GNDA |-0.3V to +6V |
| OCS, OSCLK, OSDI, OAUX, SBA | |
| to GNDA |-0.3V to (V _{DDA} + 0.3V) |
| Short-Circuit Duration | |
| OCS, OSCLK, OSDI, OAUX, SBA to V _{DDA} | |
| or GNDA |Continuous |
| OSDO, SAA to V _{DDB} or GNDB |Continuous |

| | |
|---|----------------------|
| Short Circuit Continuous Current ($\overline{\text{OFAULT}}$) | 100mA |
| Continuous Power Dissipation | |
| Single Layer Board T _A = +70°C |640mW |
| Derate above +70°C |8mW/°C |
| Multilayer Board T _A = +70°C |964mW |
| Derate above +70°C |12mW/°C |
| Operating Temperature Range |-40°C to +125°C |
| Maximum Junction Temperature |+150°C |
| Storage Temperature Range |-60°C to +150°C |
| Soldering Temperature (reflow) |+260°C |

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Package Thermal Characteristics

| | |
|---|--------------|
| Thermal Resistance, Single Layer Board | |
| Junction-to-Ambient Thermal Resistance (θ _{JA}) |125°C/W |
| Junction-to-Case Thermal Resistance (θ _{JC}) |33°C/W |

| | |
|---|-------------|
| Thermal Resistance, Four Layer Board | |
| Junction-to-Ambient Thermal Resistance (θ _{JA}) |83°C/W |
| Junction-to-Case Thermal Resistance (θ _{JC}) |33°C/W |

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to www.maximintegrated.com/thermal-tutorial.

DC Electrical Characteristics

(V_{DDA} - V_{GNDA} = 1.71V to 5.5V, V_{DDB} - V_{GNDB} = 1.71V to 5.5V, T_A = -40°C to +125°C, unless otherwise noted. Typical values are at V_{DDA} - V_{GNDA} = 3.3V, V_{DDB} - V_{GNDB} = 3.3V, V_{GNDA} = V_{GNDB}, T_A = +25°C, unless otherwise noted.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | |
|---|------------------------|--|-------------------------|-----|------|-------|----|
| POWER SUPPLY | | | | | | | |
| Supply Voltage | V _{DDA} | Relative to GNDA | 1.71 | | 5.5 | V | |
| | V _{DDB} | Relative to GNDB | 1.71 | | 5.5 | | |
| Undervoltage-Lockout Threshold | V _{UVLO_} | V _{DD_} rising | 1.5 | 1.6 | 1.66 | V | |
| Undervoltage-Lockout Threshold Hysteresis | V _{UVLO_HYST} | | | 45 | | mV | |
| Supply Current Side A (Note 2) | I _{DDA} | IRDY = 0V, SDOEN = 0V, all other inputs = 500kHz square wave, C _L = 0pF | V _{DDA} = 5V | | 1.07 | 1.86 | mA |
| | | | V _{DDA} = 3.3V | | 1.04 | 1.81 | |
| | | | V _{DDA} = 2.5V | | 1.03 | 1.79 | |
| | | | V _{DDA} = 1.8V | | 1.00 | 1.59 | |
| | | 10MHz square wave on ISCLK, 5MHz square wave on ISDO and ISDI, all other inputs = 0V, C _L = 0pF | V _{DDA} = 5V | | 1.71 | 2.59 | |
| | | | V _{DDA} = 3.3V | | 1.46 | 2.32 | |
| | | | V _{DDA} = 2.5V | | 1.39 | 2.21 | |
| | | | V _{DDA} = 1.8V | | 1.30 | 1.94 | |

DC Electrical Characteristics (continued)

($V_{DDA} - V_{GNDA} = 1.71V$ to $5.5V$, $V_{DDB} - V_{GNDB} = 1.71V$ to $5.5V$, $T_A = -40^\circ C$ to $+125^\circ C$, unless otherwise noted. Typical values are at $V_{DDA} - V_{GNDA} = 3.3V$, $V_{DDB} - V_{GNDB} = 3.3V$, $V_{GNDA} = V_{GNDB}$, $T_A = +25^\circ C$, unless otherwise noted.) (Note 1)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|-----------|---|------------------------|------|------|---------|
| Supply Current Side B (Note 2) | I_{DDB} | $\overline{IRDY} = 0V$, $\overline{SDOEN} = 0V$, all other inputs = 500kHz square wave, $C_L = 0pF$ | $V_{DDB} = 5V$ | 0.92 | 1.64 | mA |
| | | | $V_{DDB} = 3.3V$ | 0.90 | 1.59 | |
| | | | $V_{DDB} = 2.5V$ | 0.88 | 1.57 | |
| | | | $V_{DDB} = 1.8V$ | 0.86 | 1.27 | |
| | | 10MHz square wave on ISCLK, 5MHz square wave on ISDO and ISDI, all other inputs = 0V, $C_L = 0pF$ | $V_{DDB} = 5V$ | 1.46 | 2.30 | |
| | | | $V_{DDB} = 3.3V$ | 1.33 | 2.18 | |
| | | | $V_{DDB} = 2.5V$ | 1.33 | 2.14 | |
| | | | $V_{DDB} = 1.8V$ | 1.28 | 1.80 | |
| LOGIC INPUTS AND OUTPUTS | | | | | | |
| Input High Voltage | V_{IH} | $2.25V \leq V_{DD_} \leq 5.5V$ | $0.7 \times V_{DD_}$ | | | V |
| | | $1.71V \leq V_{DD_} < 2.25V$ | $0.75 \times V_{DD_}$ | | | |
| Input Low Voltage | V_{IL} | $2.25V \leq V_{DD_} \leq 5.5V$ | 0.8 | | | V |
| | | $1.71V \leq V_{DD_} < 2.25V$ | 0.7 | | | |
| Input Hysteresis | V_{HYS} | | 410 | | | mV |
| Input Pullup Current (Note 3) | I_{PU} | \overline{IAUX} , \overline{ICS} , \overline{SDOEN} , \overline{IRDY} | -10 | -5 | -1.5 | μA |
| Input Pulldown Current (Note 3) | I_{PD} | \overline{IFault} , ISDO, ISDI, ISCLK | 1.5 | 5 | 10 | μA |
| Input Capacitance | C_{IN} | $f_{SW} = 1MHz$ | 2 | | | pF |
| Output Voltage High (Note 3) | V_{OH} | $V_{O_}$ relative to $GND_$ $I_{O_} = 4mA$ source | $V_{DD_} - 0.4$ | | | V |
| Output Voltage Low (Note 3) | V_{OL} | $V_{O_}$ relative to $GND_$ $I_{O_} = 4mA$ sink | 0.4 | | | V |
| Output High-Impedance Leakage Current (Note 3) | I_{OL} | OSDO, \overline{OFault} | -1 | 1 | | μA |

Dynamic Characteristics

($V_{DDA} - V_{GNDA} = 1.71V$ to $5.5V$, $V_{DDB} - V_{GNDB} = 1.71V$ to $5.5V$, $C_L = 15pF$, $T_A = -40^{\circ}C$ to $+125^{\circ}C$, unless otherwise noted. Typical values are at $V_{DDA} - V_{GNDA} = 3.3V$, $V_{DDB} - V_{GNDB} = 3.3V$, $V_{GNDA} = V_{GNDB}$, $T_A = +25^{\circ}C$, unless otherwise noted.) (Note 2)

| PARAMETER | SYMBOL | CONDITIONS | | MIN | TYP | MAX | UNITS | |
|---|--------------------|--|---|------|------|------|-------------|----|
| LOW DATA RATE CHANNELS - \overline{IFAULT}, \overline{OFAULT}, $IAUX$, $O AUX$, \overline{ICS}, \overline{OCS} | | | | | | | | |
| Common-Mode Transient Immunity | CMTI | $I_- = GND_-$ or V_{DD_-} (Note 4) | | 50 | | | kV/ μ s | |
| Maximum Data Rate | DR _{MAX} | | | 25 | | | Mbps | |
| Minimum Pulse Width | PW _{MIN} | I_- to O_- | | 40 | | | ns | |
| Glitch Rejection | | I_- to O_- | | 10 | 17 | 29 | ns | |
| Propagation Delay (Figure 1) | t _{PLH} | I_- to O_- , $C_L = 15pF$ | $4.5V \leq V_{DD_-} \leq 5.5V$ | 17.4 | 23.9 | 32.5 | ns | |
| | | | $3.0V \leq V_{DD_-} \leq 3.6V$ | 17.6 | 24.4 | 33.7 | | |
| | | | $2.25V \leq V_{DD_-} \leq 2.75V$ | 18.3 | 25.8 | 36.7 | | |
| | | | $1.71V \leq V_{DD_-} \leq 1.89V$ | 20.7 | 29.6 | 43.5 | | |
| | | \overline{IFAULT} to \overline{OFAULT} | Open drain output, $R_{pullup} = 10k\Omega$, $C_L = 15pF$ | 150 | | | | |
| | t _{PHL} | I_- to O_- , $C_L = 15pF$ | $4.5V \leq V_{DD_-} \leq 5.5V$ | 16.9 | 23.4 | 33.6 | ns | |
| | | | $3.0V \leq V_{DD_-} \leq 3.6V$ | 17.2 | 24.2 | 35.1 | | |
| | | | $2.25V \leq V_{DD_-} \leq 2.75V$ | 17.8 | 25.4 | 38.2 | | |
| $1.71V \leq V_{DD_-} \leq 1.89V$ | | | 19.8 | 29.3 | 45.8 | | | |
| Pulse Width Distortion | PWD | t _{PLH} - t _{PHL} | | 0.4 | | | 4 | ns |
| Propagation Delay Skew Part-to-Part (Same Channel) | t _{SPLH} | $4.5V \leq V_{DD_-} \leq 5.5V$ | | 15.1 | | | ns | |
| | | $3.0V \leq V_{DD_-} \leq 3.6V$ | | 15 | | | | |
| | | $2.25V \leq V_{DD_-} \leq 2.75V$ | | 15.4 | | | | |
| | | $1.71V \leq V_{DD_-} \leq 1.89V$ | | 20.5 | | | | |
| | t _{SPHL} | $4.5V \leq V_{DD_-} \leq 5.5V$ | | 13.9 | | | | |
| | | $3.0V \leq V_{DD_-} \leq 3.6V$ | | 14.2 | | | | |
| | | $2.25V \leq V_{DD_-} \leq 2.75V$ | | 16 | | | | |
| | | $1.71V \leq V_{DD_-} \leq 1.89V$ | | 21.8 | | | | |
| Propagation Delay Skew Channel-to-Channel (Same Direction) | t _{SCSLH} | $1.71V \leq V_{DD_-} \leq 5.5V$ | | 2 | | | ns | |
| | t _{SCSHL} | $1.71V \leq V_{DD_-} \leq 5.5V$ | | 2 | | | | |

Dynamic Characteristics (continued)

($V_{DDA} - V_{GNDA} = 1.71V$ to $5.5V$, $V_{DDB} - V_{GNDB} = 1.71V$ to $5.5V$, $C_L = 15pF$, $T_A = -40^{\circ}C$ to $+125^{\circ}C$, unless otherwise noted. Typical values are at $V_{DDA} - V_{GNDA} = 3.3V$, $V_{DDB} - V_{GNDB} = 3.3V$, $V_{GNDA} = V_{GNDB}$, $T_A = +25^{\circ}C$, unless otherwise noted.) (Note 2)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | |
|--|----------------------|---|----------------------------------|-----|------|-------|----|
| Propagation Delay Skew Channel-to-Channel (Opposite Direction) | t _{SCOLH} | 4.5V ≤ V _{DD_} ≤ 5.5V | | | 13.9 | ns | |
| | | 3.0V ≤ V _{DD_} ≤ 3.6V | | | 13.7 | | |
| | | 2.25V ≤ V _{DD_} ≤ 2.75V | | | 14.2 | | |
| | | 1.71V ≤ V _{DD_} ≤ 1.89V | | | 19.4 | | |
| | t _{SCOHL} | 4.5V ≤ V _{DD_} ≤ 5.5V | | | 13 | | |
| | | 3.0V ≤ V _{DD_} ≤ 3.6V | | | 12.9 | | |
| | | 2.25V ≤ V _{DD_} ≤ 2.75V | | | 14.4 | | |
| | | 1.71V ≤ V _{DD_} ≤ 1.89V | | | 20.1 | | |
| Peak Eye Diagram Jitter | T _{JIT(PK)} | 25Mbps | | 250 | | ps | |
| Rise Time (Figure 1) | t _R | 4.5V ≤ V _{DD_} ≤ 5.5V | | | 1.6 | ns | |
| | | 3.0V ≤ V _{DD_} ≤ 3.6V | | | 2.2 | | |
| | | 2.25V ≤ V _{DD_} ≤ 2.75V | | | 3 | | |
| | | 1.71V ≤ V _{DD_} ≤ 1.89V | | | 4.5 | | |
| Fall Time (Figure 1) | t _F | 4.5V ≤ V _{DD_} ≤ 5.5V | | | 1.4 | ns | |
| | | 3.0V ≤ V _{DD_} ≤ 3.6V | | | 2 | | |
| | | 2.25V ≤ V _{DD_} ≤ 2.75V | | | 2.8 | | |
| | | 1.71V ≤ V _{DD_} ≤ 1.89V | | | 5.1 | | |
| SPI DATA RATE CHANNELS - ISDI, OSDI, ISDO, OSDO, ISCLK, OSCLK | | | | | | | |
| Common-Mode Transient Immunity | CMTI | I ₋ = GND ₋ or V _{DD_-} (Note 4) | | 50 | | kV/μs | |
| Maximum Data Rate | DR _{MAX} | 2.25V ≤ V _{DD_} ≤ 5.5V | 200 | | | Mbps | |
| | | 1.71V ≤ V _{DD_} ≤ 1.89V | 150 | | | | |
| Minimum Pulse Width | PW _{MIN} | I ₋ to O ₋ | 2.25V ≤ V _{DD_} ≤ 5.5V | | 5 | ns | |
| | | | 1.71V ≤ V _{DD_} ≤ 1.89V | | 6.67 | | |
| Propagation Delay (Figure 1) | t _{PLH} | I ₋ to O ₋ , C _L = 15pF | 4.5V ≤ V _{DD_} ≤ 5.5V | 4.1 | 5.4 | 9.2 | ns |
| | | | 3.0V ≤ V _{DD_} ≤ 3.6V | 4.2 | 5.9 | 10.2 | |
| | | | 2.25V ≤ V _{DD_} ≤ 2.75V | 4.9 | 7.1 | 13.4 | |
| | | | 1.71V ≤ V _{DD_} ≤ 1.89V | 7.1 | 10.9 | 20.3 | |
| | t _{PHL} | I ₋ to O ₋ , C _L = 15pF | 4.5V ≤ V _{DD_} ≤ 5.5V | 4.3 | 5.6 | 9.4 | |
| | | | 3.0V ≤ V _{DD_} ≤ 3.6V | 4.4 | 6.2 | 10.5 | |
| | | | 2.25V ≤ V _{DD_} ≤ 2.75V | 5.1 | 7.3 | 14.1 | |
| | | | 1.71V ≤ V _{DD_} ≤ 1.89V | 7.2 | 10.9 | 21.7 | |
| Pulse Width Distortion | PWD | t _{PLH} - t _{PHL} | | 0.3 | 2 | ns | |

Dynamic Characteristics (continued)

($V_{DDA} - V_{GNDA} = 1.71V$ to $5.5V$, $V_{DDB} - V_{GNDB} = 1.71V$ to $5.5V$, $C_L = 15pF$, $T_A = -40^\circ C$ to $+125^\circ C$, unless otherwise noted. Typical values are at $V_{DDA} - V_{GNDA} = 3.3V$, $V_{DDB} - V_{GNDB} = 3.3V$, $V_{GNDA} = V_{GNDB}$, $T_A = +25^\circ C$, unless otherwise noted.) (Note 2)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|----------------|---|--------------------------------|-----|------|-------|
| Propagation Delay Skew Part-to-Part (Same Channel) | t_{SPLH} | $4.5V \leq V_{DD} \leq 5.5V$ | | | 3.7 | ns |
| | | $3.0V \leq V_{DD} \leq 3.6V$ | | | 4.3 | |
| | | $2.25V \leq V_{DD} \leq 2.75V$ | | | 6 | |
| | | $1.71V \leq V_{DD} \leq 1.89V$ | | | 10.3 | |
| | t_{SPHL} | $4.5V \leq V_{DD} \leq 5.5V$ | | | 3.8 | |
| | | $3.0V \leq V_{DD} \leq 3.6V$ | | | 4.7 | |
| | | $2.25V \leq V_{DD} \leq 2.75V$ | | | 6.5 | |
| | | $1.71V \leq V_{DD} \leq 1.89V$ | | | 11.5 | |
| Propagation Delay Skew Channel-to-Channel (Same Direction) | t_{SCSLH} | | | | 2 | ns |
| | t_{SCSHL} | | | | 2 | |
| Propagation Delay Skew Channel-to-Channel (Opposite Direction) | t_{SCOLH} | $4.5V \leq V_{DD} \leq 5.5V$ | | | 2.9 | ns |
| | | $3.0V \leq V_{DD} \leq 3.6V$ | | | 3.4 | |
| | | $2.25V \leq V_{DD} \leq 2.75V$ | | | 4.9 | |
| | | $1.71V \leq V_{DD} \leq 1.89V$ | | | 10.2 | |
| | t_{SCOHL} | $4.5V \leq V_{DD} \leq 5.5V$ | | | 3.2 | |
| | | $3.0V \leq V_{DD} \leq 3.6V$ | | | 3.8 | |
| | | $2.25V \leq V_{DD} \leq 2.75V$ | | | 5.3 | |
| | | $1.71V \leq V_{DD} \leq 1.89V$ | | | 10.9 | |
| Peak Eye Diagram Jitter | $T_{JIT(PK)}$ | 200Mbps | | 250 | | ps |
| Clock Jitter RMS | $T_{JCK(RMS)}$ | 500kHz Clock Input, Rising/Falling Edges | | 6.5 | | ps |
| Rise Time | t_R | $4.5V \leq V_{DD} \leq 5.5V$ | | | 1.6 | ns |
| | | $3.0V \leq V_{DD} \leq 3.6V$ | | | 2.2 | |
| | | $2.25V \leq V_{DD} \leq 2.75V$ | | | 3 | |
| | | $1.71V \leq V_{DD} \leq 1.89V$ | | | 4.5 | |
| Fall Time | t_F | $4.5V \leq V_{DD} \leq 5.5V$ | | | 1.4 | ns |
| | | $3.0V \leq V_{DD} \leq 3.6V$ | | | 2 | |
| | | $2.25V \leq V_{DD} \leq 2.75V$ | | | 2.8 | |
| | | $1.71V \leq V_{DD} \leq 1.89V$ | | | 5.1 | |
| Enable to Data Valid | t_{EN} | \overline{ICS} or \overline{SDOEN} falling to OSDO valid, $C_L = 15pF$ | $4.5V \leq V_{DD} \leq 5.5V$ | | 31.3 | ns |
| | | | $3.0V \leq V_{DD} \leq 3.6V$ | | 34.8 | |
| | | | $2.25V \leq V_{DD} \leq 2.75V$ | | 40.0 | |
| | | | $1.71V \leq V_{DD} \leq 1.89V$ | | 51.8 | |
| Disable to Tri-state | t_{TRI} | \overline{ICS} or \overline{SDOEN} rising to OSDO tristate, $C_L = 15pF$ | $4.5V \leq V_{DD} \leq 5.5V$ | | 33.9 | ns |
| | | | $3.0V \leq V_{DD} \leq 3.6V$ | | 38.6 | |
| | | | $2.25V \leq V_{DD} \leq 2.75V$ | | 44.4 | |
| | | | $1.71V \leq V_{DD} \leq 1.89V$ | | 55 | |

Dynamic Characteristics (continued)

($V_{DDA} - V_{GNDA} = 1.71V$ to $5.5V$, $V_{DDB} - V_{GNDB} = 1.71V$ to $5.5V$, $C_L = 15pF$, $T_A = -40^{\circ}C$ to $+125^{\circ}C$, unless otherwise noted. Typical values are at $V_{DDA} - V_{GNDA} = 3.3V$, $V_{DDB} - V_{GNDB} = 3.3V$, $V_{GNDA} = V_{GNDB}$, $T_A = +25^{\circ}C$, unless otherwise noted.) (Note 2)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|-----------|--------------------------------------|-----|-----|-----|-------------|
| CONTROL AND MONITOR CHANNELS - \overline{IRDY}, \overline{SDOEN}, SAA, SBA | | | | | | |
| Common-Mode Transient Immunity | CMTI | $I_- = GND_-$ or V_{DD_-} (Note 4) | | 50 | | kV/ μ s |
| Glitch Rejection | | \overline{SDOEN} | 10 | 17 | 29 | ns |
| Propagation Delay | t_{PLH} | \overline{IRDY} low to high | | 100 | | μ s |
| | t_{PHL} | \overline{IRDY} high to low | | 100 | | |
| Rise Time | t_R | $4.5V \leq V_{DD_-} \leq 5.5V$ | | | 1.6 | ns |
| | | $3.0V \leq V_{DD_-} \leq 3.6V$ | | | 2.2 | |
| | | $2.25V \leq V_{DD_-} \leq 2.75V$ | | | 3 | |
| | | $1.71V \leq V_{DD_-} \leq 1.89V$ | | | 4.5 | |
| Fall Time | t_F | $4.5V \leq V_{DD_-} \leq 5.5V$ | | | 1.4 | ns |
| | | $3.0V \leq V_{DD_-} \leq 3.6V$ | | | 2 | |
| | | $2.25V \leq V_{DD_-} \leq 2.75V$ | | | 2.8 | |
| | | $1.71V \leq V_{DD_-} \leq 1.89V$ | | | 5.1 | |

- Note 1:** All devices are 100% production tested at $T_A = +25^{\circ}C$. Specifications over temperature are guaranteed by design.
- Note 2:** Not production tested. Guaranteed by design and characterization.
- Note 3:** All currents into the device are positive. All currents out of the device are negative. All voltages are referenced to their respective ground (GNDA or GNDB), unless otherwise noted.
- Note 4:** CMTI is the maximum sustainable common-mode voltage slew rate while maintaining the correct output. CMTI applies to both rising and falling common-mode voltage edges. Tested with the transient generator connected between GNDA and GNDB ($V_{CM} = 1000V$).

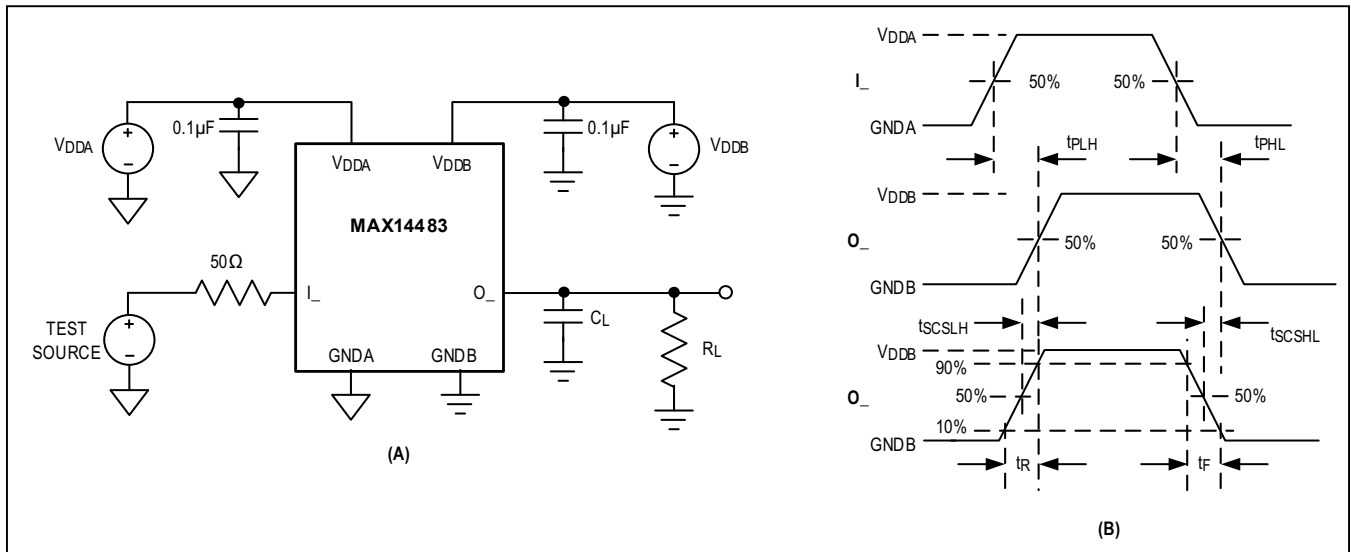


Figure 1. Test Circuit (A) and Timing Diagram (B)

ESD Protection

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|-----------|--------|----------------------------|-----|-----|-----|-------|
| ESD | | Human Body Model, all pins | | ±4 | | kV |

Insulation Characteristics

Table 1. 20-pin SSOP Insulation Characteristics

| PARAMETER | SYMBOL | CONDITIONS | VALUE | UNITS |
|---|-------------------|--|-------------------|------------------|
| Partial Discharge Test Voltage | V _{PR} | Method B1 = V _{IORM} × 1.875 (t = 1s, partial discharge < 5pC) | 1050 | V _P |
| Maximum Repetitive Peak Isolation Voltage | V _{IORM} | (Note 5) | 560 | V _P |
| Maximum Working Isolation Voltage | V _{IOWM} | Continuous RMS voltage (Note 5) | 400 | V _{RMS} |
| Maximum Transient Isolation Voltage | V _{IOTM} | t = 1s | 5300 | V _P |
| Maximum Withstand Isolation Voltage | V _{ISO} | f _{SW} = 60Hz, duration = 60s (Note 5, 6) | 3750 | V _{RMS} |
| Maximum Surge Isolation Voltage | V _{IOSM} | Basic Insulation, 1.2/50μs pulse per IEC61000-4-5 | 10 | kV |
| Insulation Resistance | R _{IO} | V _{IO} = 500V, T _A = 25°C | >10 ¹² | Ω |
| | | V _{IO} = 500V, 100°C ≤ T _A ≤ 125°C | >10 ¹¹ | |
| | | V _{IO} = 500V, T _S = 150°C | >10 ⁹ | |
| Barrier Capacitance Side A to Side B | C _{IO} | f _{SW} = 1MHz (Note 7) | 1.5 | pF |
| Minimum Creepage Distance | CPG | SSOP | 5.5 | mm |
| Minimum Clearance Distance | CLR | SSOP | 5.5 | mm |
| Internal Clearance | | Distance through insulation | 0.015 | mm |
| Comparative Tracking Index | CTI | Material Group II (IEC 60112) | >400 | |
| Climate Category | | | 40/125/21 | |
| Pollution Degree (DIN VDE 0110, Table 1) | | | 2 | |

Note 5: V_{ISO}, V_{IOWM}, and V_{IORM} are defined by the IEC 60747-5-5 standard.

Note 6: Product is qualified at V_{ISO} for 60s and 100% production tested at 120% of V_{ISO} for 1s.

Note 7: Capacitance is measured with all pins on side A and side B tied together.

Safety Limits

Damage to the IC can result in a low-resistance path to ground or to the supply and, without current limiting, the MAX14483 could dissipate excessive amounts of power. Excessive power dissipation can damage the die and result in damage to the isolation barrier, potentially causing downstream issues. [Table 2](#) shows the safety limits for the MAX14483.

The maximum safety temperature (T_S) for the device is the 150°C maximum junction temperature specified in the [Absolute Maximum Ratings](#). The power dissipation (P_D) and junction-to-ambient thermal impedance (θ_{JA}) determine

the junction temperature. Thermal impedance values (θ_{JA} and θ_{JC}) are available in the [Package Thermal Characteristics](#) section of the datasheet and power dissipation calculations are discussed in the Calculating Power Dissipation section. Calculate the junction temperature (T_J) as:

$$T_J = T_A + (P_D \times \theta_{JA})$$

[Figure 2](#) and [Figure 3](#) show the thermal derating curve for safety limiting the power and the current of the device. Ensure that the junction temperature does not exceed 150°C.

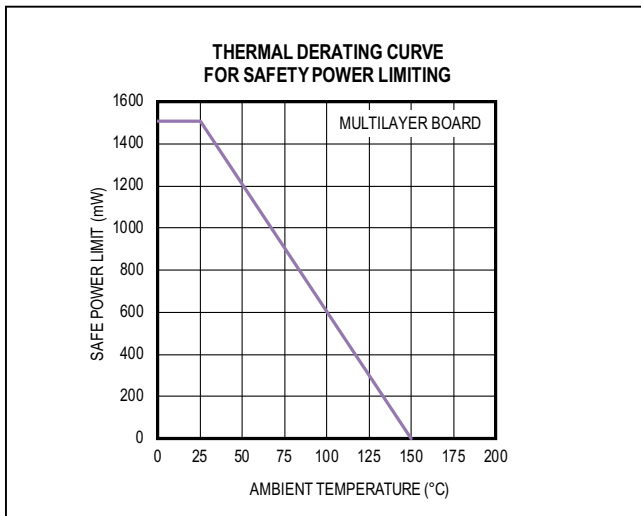


Figure 2. Thermal Derating Curve for Safety Power Limiting

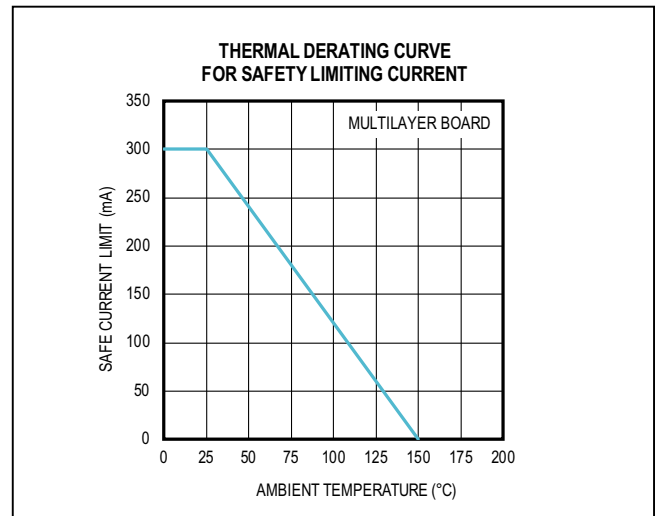


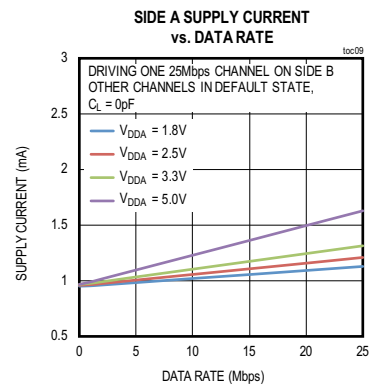
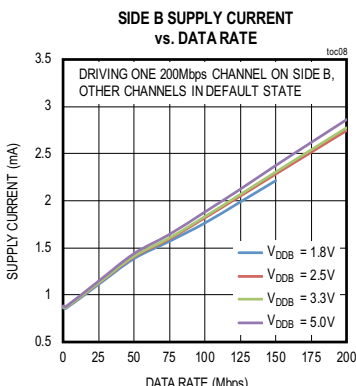
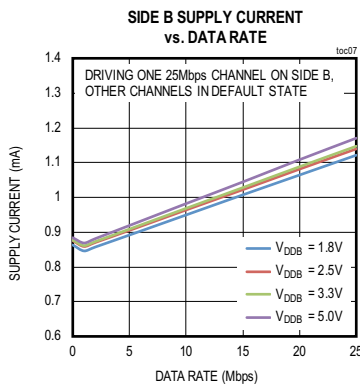
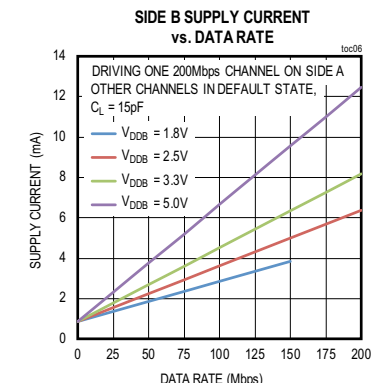
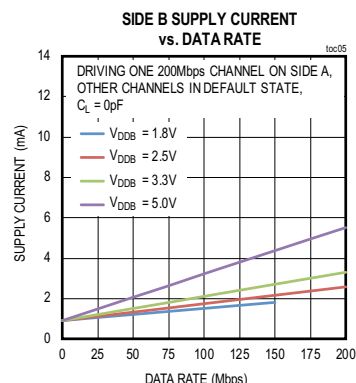
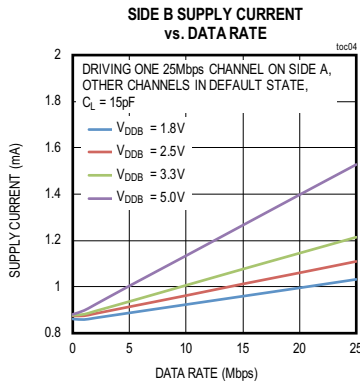
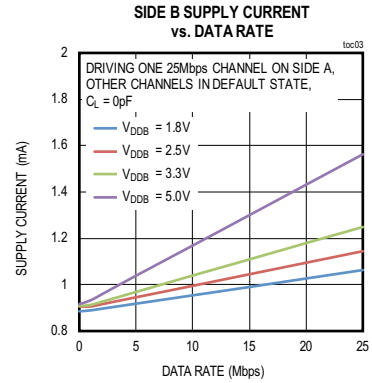
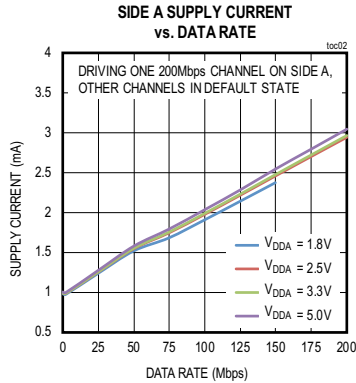
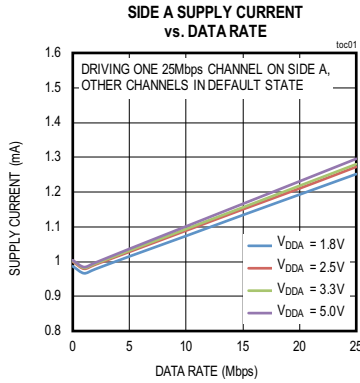
Figure 3. Thermal Derating Curve for Safety Current Limiting

Table 2. Safety Limiting Values for the MAX14483

| PARAMETER | SYMBOL | TEST CONDITIONS | MAX | UNIT |
|--------------------------------|--------|---|------|------|
| Safety Current on Any Pin | I_S | $T_J = 150^\circ\text{C}$, $T_A = 25^\circ\text{C}$, Multilayer Board | 300 | mA |
| Total Safety Power Dissipation | P_S | $T_J = 150^\circ\text{C}$, $T_A = 25^\circ\text{C}$, Multilayer Board | 1506 | mW |
| Maximum Safety Temperature | T_S | | 150 | °C |

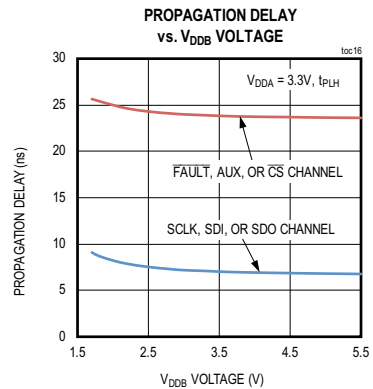
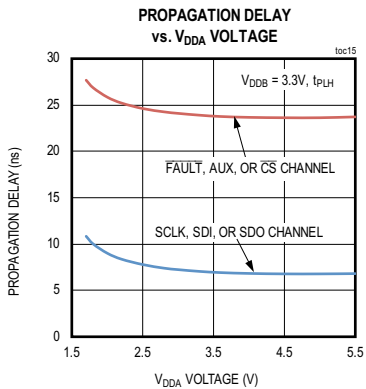
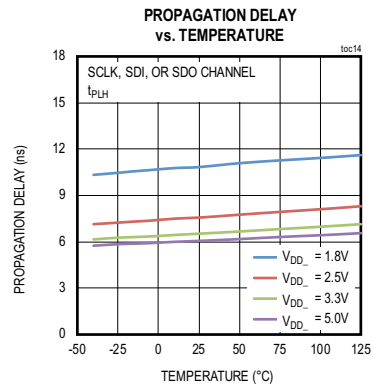
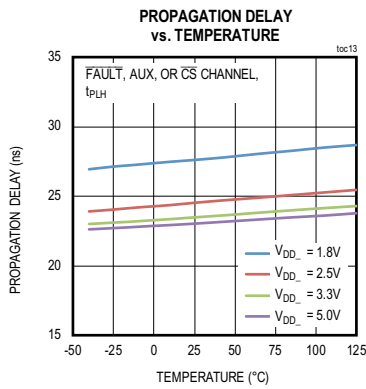
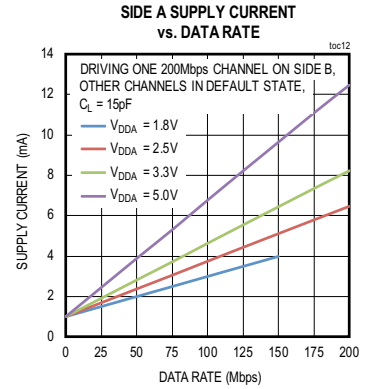
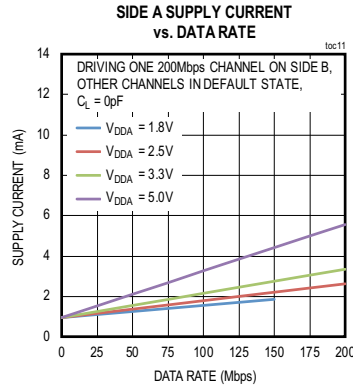
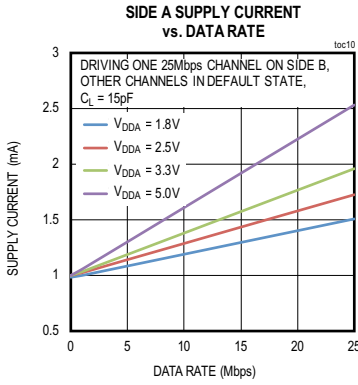
Typical Operating Characteristics

($V_{DDA} - V_{GNDA} = +3.3V$, $V_{DDB} - V_{GNDB} = +3.3V$, $V_{GNDA} = V_{GNDB}$, $T_A = +25^\circ C$, unless otherwise noted.)



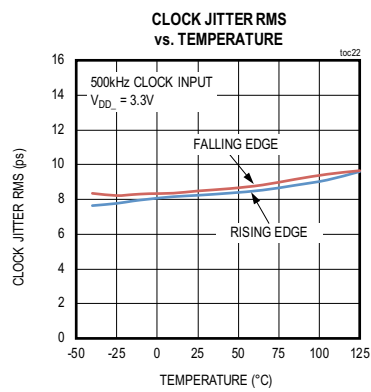
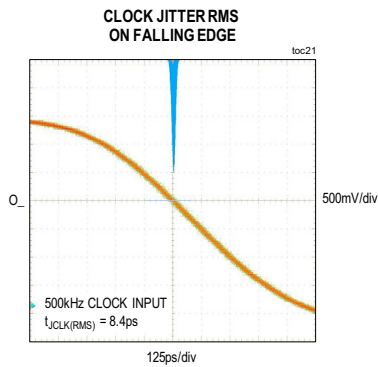
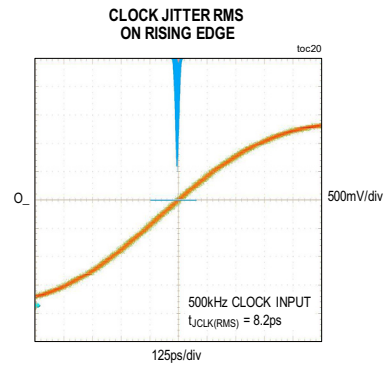
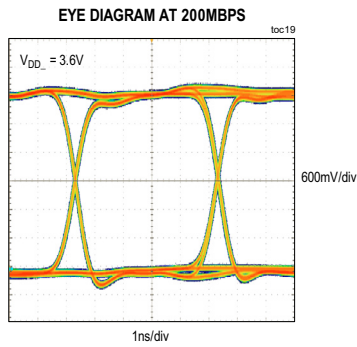
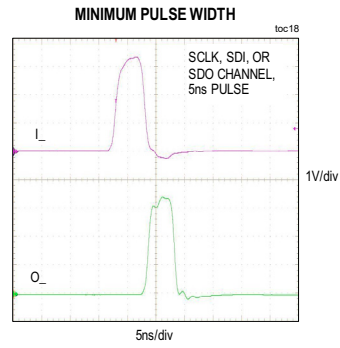
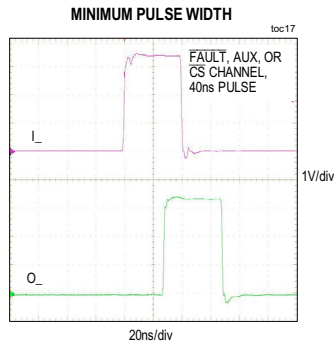
Typical Operating Characteristics (continued)

($V_{DDA} - V_{GNDA} = +3.3V$, $V_{DDB} - V_{GNDB} = +3.3V$, $V_{GNDA} = V_{GNDB}$, $T_A = +25^\circ C$, unless otherwise noted.)

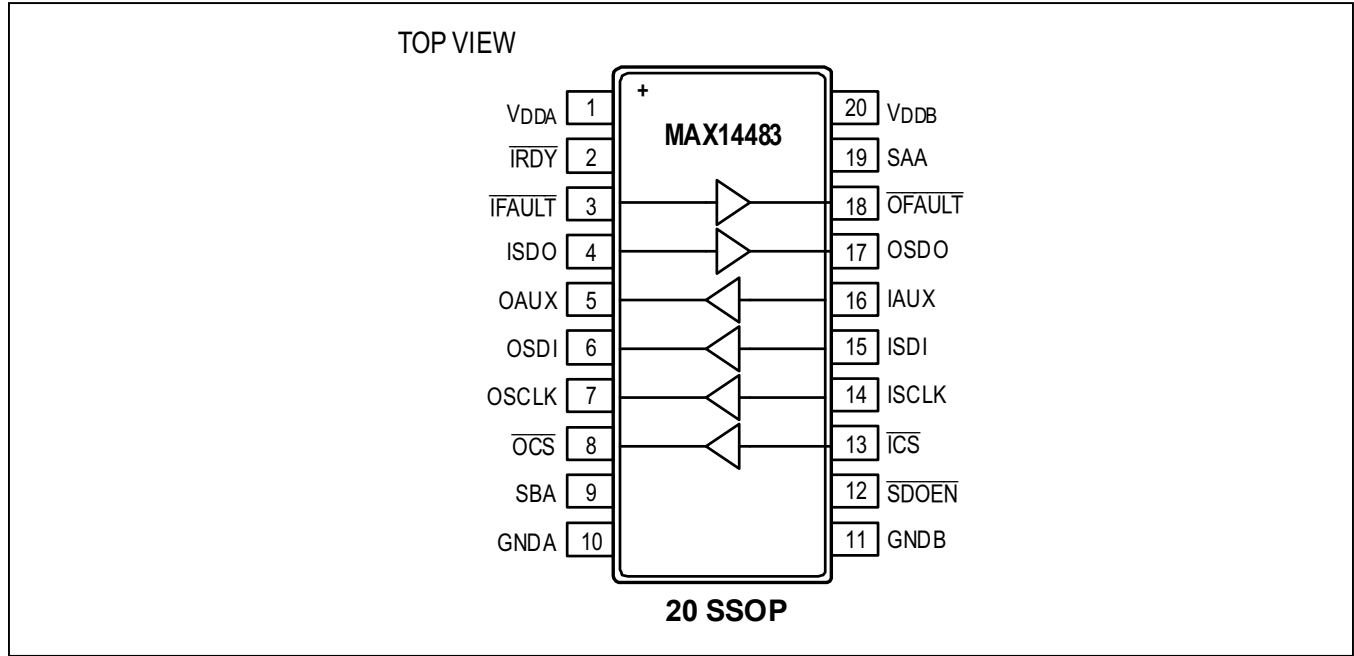


Typical Operating Characteristics (continued)

($V_{DDA} - V_{GNDA} = +3.3V$, $V_{DDB} - V_{GNDB} = +3.3V$, $V_{GNDA} = V_{GNDB}$, $T_A = +25^\circ C$, unless otherwise noted.)



Pin Configurations



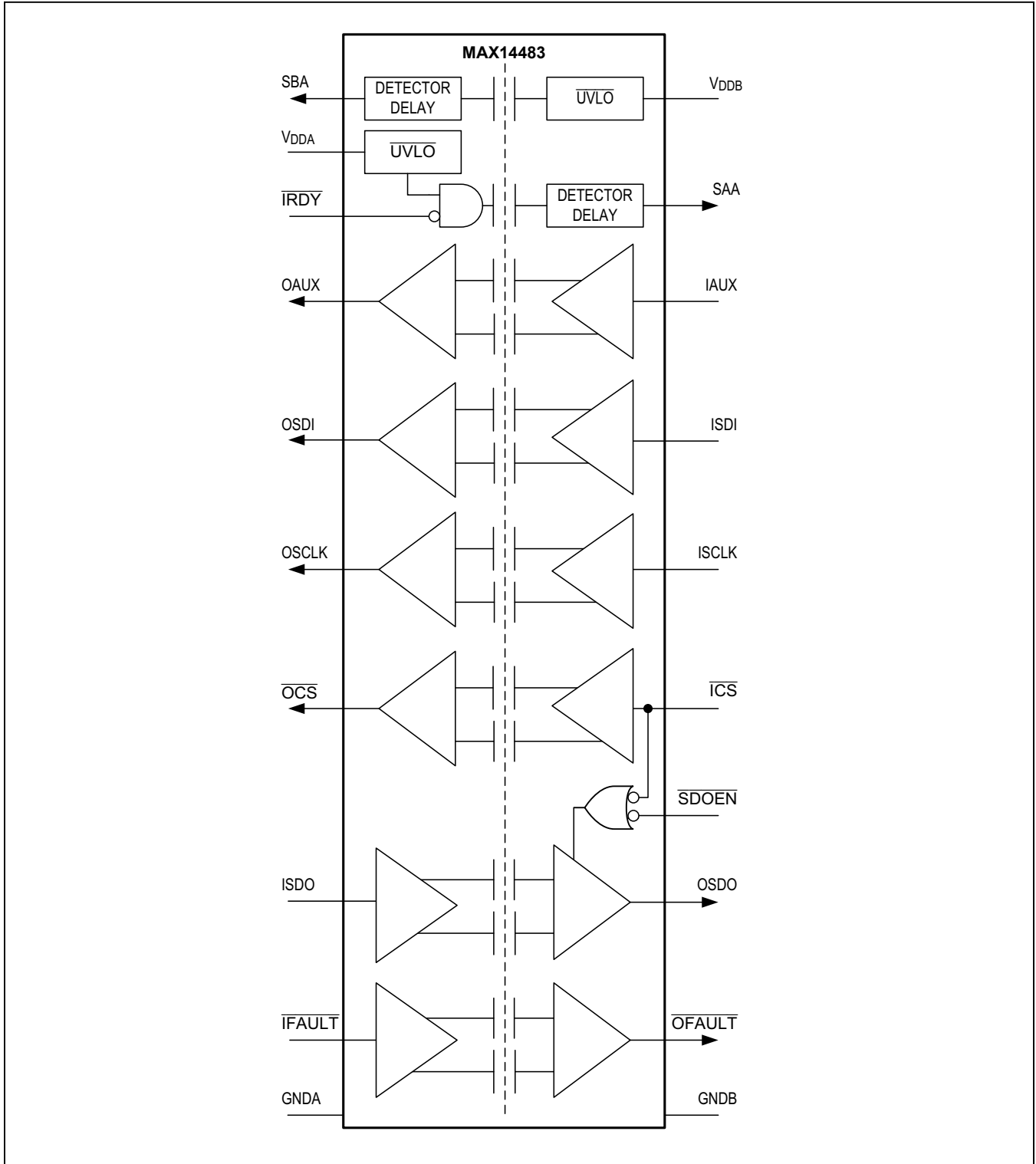
Pin Description

| PIN | NAME | FUNCTION | REFERENCE |
|---------------------------|------------------|---|-----------|
| SIDE A (SPI SLAVE) | | | |
| 1 | V _{DDA} | Power Supply. Bypass V _{DDA} with a 0.1µF ceramic capacitor as close as possible to the pin. | GNDA |
| 2 | IRDY | Ready Input. Assert IRDY low when Side A is ready for communication. When IRDY is high, SAA is low and Side B outputs are in their default state (OFAULT is low and OSDO is low when enabled). When IRDY is low, and Side A power is valid, SAA is high and Side B outputs operate normally. If the ready function is not required, tie IRDY to GNDA. | GNDA |
| 3 | IFAULT | Input to FAULT channel; has a weak internal pulldown. | GNDA |
| 4 | ISDO | Input to SDO channel; has a weak internal pulldown. Connect to MISO of slave device(s). | GNDA |
| 5 | OAUX | Output of AUX channel. | GNDA |
| 6 | OSDI | Output of SDI channel. Connect to MOSI of slave device(s). | GNDA |
| 7 | OSCLK | Output of SCLK channel. Connect to SCLK of slave device(s). | GNDA |
| 8 | OCS | Output of CS channel. Connect to CS of slave device(s). | GNDA |

Pin Description (continued)

| PIN | NAME | FUNCTION | REFERENCE |
|----------------------------|----------------------------|--|-----------|
| 9 | SBA | Side B Active. SBA is high when Side B has power and is operating normally. When Side B is not powered, SBA is set low and all Side A outputs are in their default state. A nominal 100µs delay is added between the detection of Side B power and the assertion of SBA. This allows time for the power supply to settle, and ensures a minimum low pulse width for SBA. | GNDA |
| 10 | GNDA | Power and Signal Ground for Side A | GNDA |
| SIDE B (SPI MASTER) | | | |
| 20 | V _{DDB} | Power Supply. Bypass V _{DDB} with a 0.1µF ceramic capacitor as close as possible to the pin. | GNDB |
| 19 | SAA | Side A Active. SAA is high when Side A has power, is operating normally, and $\overline{\text{IRDY}}$ is low. When Side A is not powered, SAA is set low and all Side B outputs are in their default state ($\overline{\text{OFAULT}}$ is low and OSDO is low when enabled). A nominal 100µs delay is added between the detection of Side A power and the assertion of SAA. This allows time for the power supply to settle, and ensures a minimum low pulse width for SAA. | GNDB |
| 18 | $\overline{\text{OFAULT}}$ | Output of $\overline{\text{FAULT}}$ channel. Open Drain Output | GNDB |
| 17 | OSDO | Output of SDO channel. Tri-stated when $\overline{\text{ICS}}$ and $\overline{\text{SDOEN}}$ are both high. Connect to MISO of SPI master. | GNDB |
| 16 | IAUX | Input to AUX channel; has a weak internal pullup to V _{DDB} | GNDB |
| 15 | ISDI | Input to SDI channel; has a weak internal pulldown. Connect to MOSI of SPI master. | GNDB |
| 14 | ISCLK | Input to SCLK channel; has a weak internal pulldown. Connect to SCLK of SPI master. | GNDB |
| 13 | $\overline{\text{ICS}}$ | Input to $\overline{\text{CS}}$ channel; has a weak internal pullup to V _{DDB} . Connect to $\overline{\text{CS}}$ output or GPO of SPI master. When $\overline{\text{ICS}}$ is low, OSDO output is enabled. | GNDB |
| 12 | $\overline{\text{SDOEN}}$ | SDO Enable; has a weak internal pullup to V _{DDB} . When $\overline{\text{SDOEN}}$ is low, the OSDO output is enabled, allowing the SDO channel to be used with multiple side A SPI slaves. | GNDB |
| 11 | GNDB | Power and Signal Ground for Side B | GNDB |

Functional Diagram



Detailed Description

The MAX14483 is a 6-channel, 3.75kV_{RMS} digital galvanic isolator using Maxim's proprietary process technology. The six signal channels are individually optimized for SPI applications and include very low propagation delay on the SDI, SDO, and SCLK channels. The SDO channel's tri-state control is enabled by the \overline{CS} input as well as a second enable control input pin (\overline{SDOEN}), allowing a single MAX14483 to isolate multiple SPI devices. To simplify system design, an open drain \overline{FAULT} output can be wire ORed with error outputs from other devices. In addition, an auxiliary channel (AUX) is available for passing timing or control signals from the master side to the slave side and power monitors (SAA, SBA) are provided for both power domains to signal that the opposite side of the isolator is ready for operation. Independent 1.71V to 5.5V supplies on each side of the isolator also make the device suitable for use as a level translator.

The MAX14483 offers low-power operation, high electromagnetic interference (EMI) immunity, and stable temperature performance through Maxim's proprietary process technology. The device isolates different ground domains and blocks high-voltage/high-current transients from sensitive or human interface circuitry.

The MAX14483 is available with a maximum data rate of 200Mbps (SPI Data Rate Channels). The device has two supply inputs (V_{DDA} and V_{DDB}) that independently set the logic levels on either side of device. V_{DDA} and V_{DDB} are referenced to $GNDA$ and $GNDB$, respectively.

The MAX14483 also features an internal refresh circuit to ensure output accuracy when an input remains in the same state indefinitely.

Digital Isolation

The MAX14483 provides galvanic isolation for digital signals that are transmitted between two ground domains. The device withstands up to 560V_{PEAK} of continuous isolation and up to 3.75kV_{RMS} for up to 60 seconds in the 20-pin SSOP package, which has 5.5mm of creepage and clearance. The package material has a minimum comparative tracking index (CTI) of 400V, giving it a group 2 rating in creepage tables.

Level-Shifting

The wide supply voltage range of both V_{DDA} and V_{DDB} allows the MAX14483 to be used for level translation in addition to isolation. V_{DDA} and V_{DDB} can be independently set to any voltage from 1.71V to 5.5V. The supply voltage sets the logic level on the corresponding side of the isolator.

Isolation Channels

The MAX14483 has three types of channels (Table 3). Low Data Rate Channels are \overline{FAULT} , AUX and \overline{CS} . SPI Data Rate Channels are SCLK, SDI, and SDO. Control and Monitor Channels are \overline{IRDY} , \overline{SDOEN} , SAA and SBA. Different types of channels have different electrical specifications.

Low Data Rate Channels

The Low Data Rate Channels are \overline{FAULT} , AUX, and \overline{CS} . Each channel is unidirectional; it only passes data in one direction, as indicated in the functional diagram. Each channel has a maximum data rate of 25Mbps. The \overline{FAULT} and AUX channels are designed to support SPI devices which require control signals beyond the standard 4-wire SPI bus. The output drivers of AUX and \overline{CS} channels are push-pull, eliminating the need for pullup resistors. The \overline{FAULT} channel output is open drain and requires a pullup resistor. All the outputs are able to drive both TTL and CMOS logic inputs. The input channels have an integrated glitch filter to help operate in noisy environments and avoid false triggering.

SPI Data Rate Channels

The SPI Data Rate Channels are SCLK, SDI, and SDO; these channels are designed to support standard 4-wire SPI bus signals (\overline{CS} is considered as a Low Data Rate Channel). Each channel is unidirectional; it only passes data in one direction, as indicated in the functional diagram. Each channel has been optimized for fast data rate and minimal skew between channels, with a maximum data rate of 200Mbps and maximum channel-to-channel propagation delay skew of only 10.2ns with $V_{DD} = 1.8V$. The output driver of each channel is push-pull, eliminating the need for pullup resistors. The outputs are able to drive both TTL and CMOS logic inputs.

Control and Monitor Channels

The Control and Monitor Channels are $\overline{\text{IRDY}}$, $\overline{\text{SDOEN}}$, SAA and SBA. Each channel is unidirectional; it only passes data in one direction, as indicated in the functional diagram. The monitor channels (SAA, SBA) are designed to pass essentially DC signals and have significantly longer propagation delays than other channels, meaning they should not be used for data signals. The outputs are able to drive both TTL and CMOS logic inputs. SAA and SBA are set high when their respective opposite side of the isolator has power and is operating normally. When Side A or Side B is not powered, SAA or SBA is set low and all outputs are set to their default state (OSDO is high impedance when disabled). A nominal 100µs delay is added between the detection of the opposite side power and the assertion of SAA or SBA. This allows time for the power supply to settle, and ensures a minimum low pulse width for SAA and SBA.

The control channels ($\overline{\text{IRDY}}$, $\overline{\text{SDOEN}}$) have an integrated glitch filter. $\overline{\text{IRDY}}$ is an external input from the A side circuits (such as a Digital I/O device) to indicate that these devices are powered and active, allowing the B side circuit (such as a MCU SPI Master) to initiate data transfer across the isolation barrier. $\overline{\text{SDOEN}}$ is an output enable control for OSDO. $\overline{\text{SDOEN}}$ allows the B side of the MAX14483 to be shared with multiple SPI devices on the A side by enabling OSDO when $\overline{\text{ICS}}$ is not asserted. The A side SPI devices can be configured either in the daisy chain mode, where a single $\overline{\text{CS}}$ signal enables all Side A devices as well as the OSDO output, or in the independent slave mode, where one Side A device uses the $\overline{\text{CS}}$ channel in the MAX14483 and the rest of the Side A devices have their own $\overline{\text{CS}}$ isolator channels, external to the MAX14483. The independent slave mode requires OSDO to be enabled any time one of the $\overline{\text{CS}}$ signals is asserted, which can be accomplished by

Table 3. Channel Summary

| CHANNEL TYPE | CHANNEL | OUTPUT DEFAULT | INPUT CURRENT SOURCE | GLITCH FILTER |
|---------------------|---------------------------|--|----------------------|---------------|
| Low Data Rate | $\overline{\text{FAULT}}$ | Low | Pull Down | Yes |
| Low Data Rate | AUX | High | Pull Up | Yes |
| Low Data Rate | $\overline{\text{CS}}$ | High | Pull Up | Yes |
| SPI Data Rate | SDI | Low | Pull Down | No |
| SPI Data Rate | SCLK | Low | Pull Down | No |
| SPI Data Rate | SDO | Low | Pull Down | No |
| Control and Monitor | $\overline{\text{SDOEN}}$ | Input Only | Pull Up | Yes |
| Control and Monitor | $\overline{\text{IRDY}}$ | Input Only | Pull Up | Yes |
| Control and Monitor | SAA | High when Side A has power, is operating normally, and $\overline{\text{IRDY}}$ is low. Low when Side A is not powered or $\overline{\text{IRDY}}$ is high. | N/A | N/A |
| Control and Monitor | SBA | High when Side B has power and is operating normally. Low when Side B is not powered. | N/A | N/A |

Table 4. Output Behavior During Undervoltage Conditions

| V_{IN_-} I_- | V_{DDA} | V_{DDB} | V_{OUTA} | SDO ENABLE | V_{OUTB} | |
|----------------------------|------------------|------------------|-------------------|------------|-------------------|----------------------------|
| | | | O_- | | OSDO | $\overline{\text{OFAULT}}$ |
| 1 | Powered | Powered | 1 | 0 | Hi-Z | 1 |
| | | | 1 | 1 | 1 | 1 |
| 0 | Powered | Powered | 0 | 0 | Hi-Z | 0 |
| | | | 0 | 1 | 0 | 0 |
| X | Undervoltage | Powered | Default | 0 | Hi-Z | Default |
| | | | Default | 1 | Default | Default |
| X | Powered | Undervoltage | Default | 0 | Hi-Z | Default |
| | | | Default | 1 | Default | Default |

connecting a GPO pin to $\overline{\text{SDOEN}}$ and asserting it any time any $\overline{\text{CS}}$ signal is asserted. In the case that the B side of the MAX14483 is not shared with multiple SPI devices, there is no need for OSD0 to be high impedance, and $\overline{\text{SDOEN}}$ can be permanently connected to GND. Refer to [Typical Operating Circuits](#) for details.

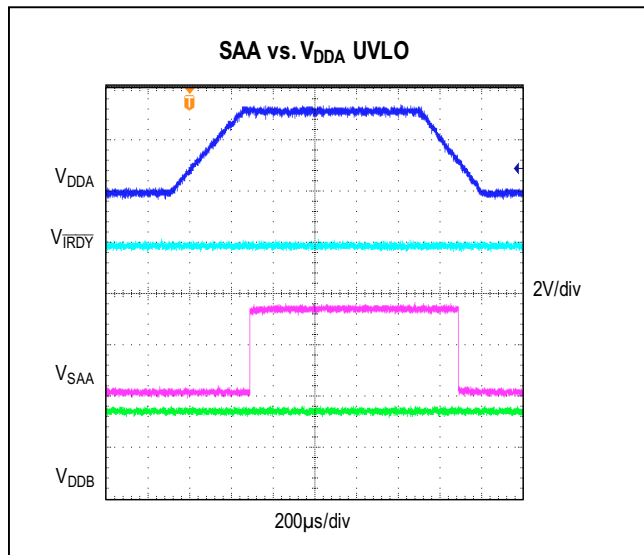


Figure 4. V_{DDA} - UVLO Controlling SAA Signal

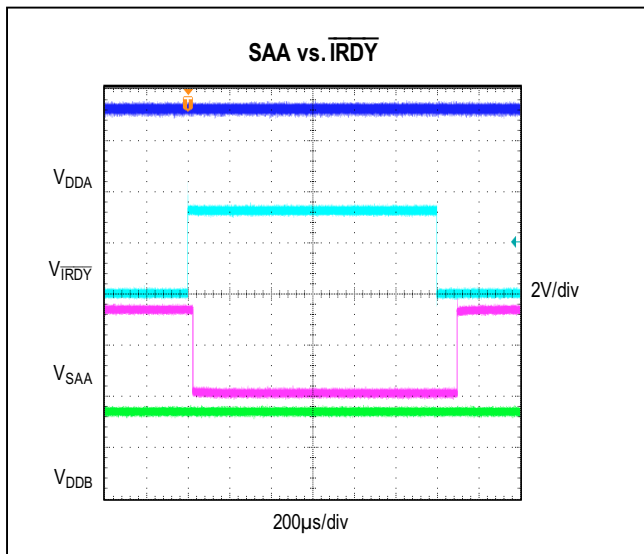


Figure 5. $\overline{\text{IRDY}}$ Controlling SAA Signal

Startup and Undervoltage-Lockout

The V_{DDA} and V_{DDB} supplies are both internally monitored for undervoltage conditions. Undervoltage events can occur during power-up, power-down, or during normal operation due to a sagging supply voltage. When an undervoltage condition is detected on either supply, all outputs go to their default states regardless of the state of the inputs (Table 4). Figure 4 through Figure 6 show the behavior of the SAA and SBA signals during power-up, power-down and $\overline{\text{IRDY}}$ toggling.

Applications Information

Power-Supply Sequencing

The MAX14483 does not require special power supply sequencing. The logic levels are set independently on either side by V_{DDA} and V_{DDB} . Each supply can be present over the entire specified range regardless of the level or presence of the other supply.

Power-Supply Decoupling

To reduce ripple and the chance of introducing data errors, bypass V_{DDA} and V_{DDB} with 0.1µF low-ESR ceramic capacitors to GND and GND, respectively. Place the bypass capacitors as close to the power supply input pins as possible.

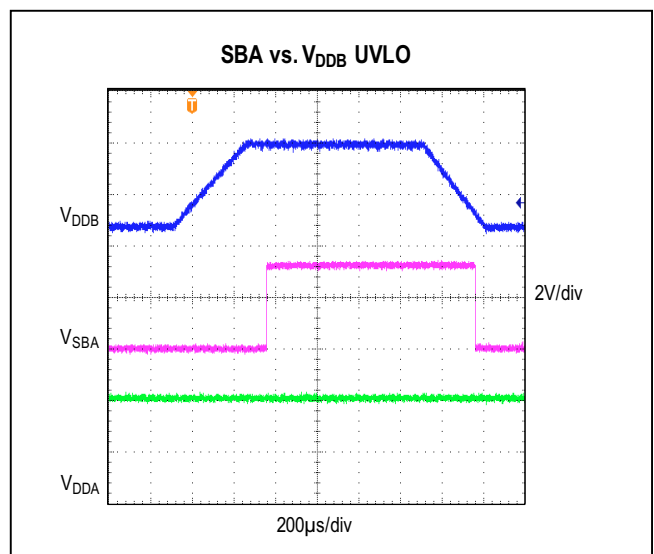


Figure 6. V_{DDB} - UVLO Controlling SBA Signal

Layout Considerations

The PCB designer should follow some critical recommendations in order to get the best performance from the design.

- Keep the input/output traces as short as possible. Avoid using vias to make low-inductance paths for the signals.
- Have a solid ground plane underneath the high-speed signal layer.
- Keep the area underneath the MAX14483 free from ground and signal planes. Any galvanic or metallic connection between the Side A and the Side B defeats the isolation.

Calculating Power Dissipation

The required current for a given supply (V_{DDA} or V_{DDB}) can be estimated by summing the current required for each channel. The supply current for a channel depends on whether the channel is an input or an output, the channel's data rate, and the capacitive or resistive load if it is an output. The typical current for an input or output at any data rate can be estimated from the graphs in [Figure 7](#) and [Figure 8](#). Please note the data in [Figure 7](#) and [Figure 8](#) are extrapolated from the supply current measurements in a typical operating condition.

The total current for a single channel is the sum of the "no load" current (shown in [Figure 7](#) and [Figure 8](#)), which is a function of Voltage and Data Rate, and the "load current", which depends on the type of load. Current into a capacitive load is a function of the load capacitance, the switching frequency, and the supply voltage.

$$I_{CL} = C_L \times f_{SW} \times V_{DD}$$

where

I_{CL} is the current required to drive the capacitive load.

C_L is the load capacitance on the isolator's output pin.

f_{SW} is the switching frequency (bits per second / 2).

V_{DD} is the supply voltage on the output side of the isolator.

Current into a resistive load depends on the resistance, the supply voltage and the average duty cycle of the data waveform. The DC load current can be conservatively estimated by assuming the output is always high.

$$I_{RL} = V_{DD} \div R_L$$

where

I_{RL} is the current required to drive the resistive load.

V_{DD} is the supply voltage on the output side of the isolator.

R_L is the load resistance on the isolator's output pin.

In the case of an SPI bus which often has intermittent read or write cycles, one other factor to consider is the active duty cycle percentage as well as the typical active current.

Example (shown in [Figure 9](#)): An SPI Master running at 10MHz and with 8-bit data package. The MAX14483 is operating with $V_{DDB} = 2.5V$, $V_{DDA} = 3.3V$, SCLK operating at 20Mbps with a 15pF load, SDI and SDO channels operating in 8-bit data frame at 10Mbps with a 15pF load on each, \overline{CS} operating at effective rate of 2.5Mbps (20Mbps divide by 8) with a 15pF load, and AUX channel operating at 1Mbps with a 10pF load. Channels SAA and SBA are not in use and FAULT drives a resistive load when active. Refer to [Table 5](#) and [Table 6](#) for V_{DDA} and V_{DDB} supply current calculation worksheets.

V_{DDA} must supply:

- ISDO operating at 3.3V and 10Mbps, consuming 0.24mA, estimated from [Figure 7](#).
- \overline{FAULT} operating at 3.3V and DC, consuming 0.14mA, estimated from [Figure 7](#).
- OAUX operating at 3.3V and 1Mbps, consuming 0.19mA, estimated from [Figure 8](#). I_{CL} on OAUX for 10pF capacitor at 3.3V is 0.017mA.
- OSDI operating at 3.3V and 10Mbps, consuming 0.30mA, estimated from [Figure 8](#). I_{CL} on OSDI for 15pF capacitor at 3.3V is 0.25mA.
- OSCLK operating at 3.3V and 20Mbps, consuming 0.42mA, estimated from [Figure 8](#). I_{CL} on OSCLK for 15pF capacitor at 3.3V is 0.50mA.
- \overline{OCS} operating at 3.3V and 2.5Mbps, consuming 0.21mA, estimated from [Figure 8](#). I_{CL} on OCS for 15pF capacitor at 3.3V is 0.062mA.

Total current for side A = 2.33mA, typical.

V_{DDB} must supply:

- IAUX operating at 2.5V and 1Mbps, consuming 0.15mA, estimated from [Figure 7](#).
- ISDI operating at 2.5V and 10Mbps, consuming 0.23mA, estimated from [Figure 7](#).
- ISCLK operating at 2.5V and 20Mbps, consuming 0.33mA, estimated from [Figure 7](#).
- \overline{ICS} operating at 2.5V and 2.5Mbps, consuming 0.16mA, estimated from [Figure 7](#).
- OSDO operating at 2.5V and 10Mbps, consuming 0.27mA, estimated from [Figure 8](#). I_{CL} on OSDO for 15pF capacitor at 2.5V is 0.19mA.
- \overline{OFAULT} operating at 2.5V and 1Mbps, consuming 0.18mA, estimated from [Figure 8](#). I_{RL} on \overline{OFAULT} for 10k Ω resistor at 2.5V is 0.25mA.

Total current for side B = 1.76mA, typical.

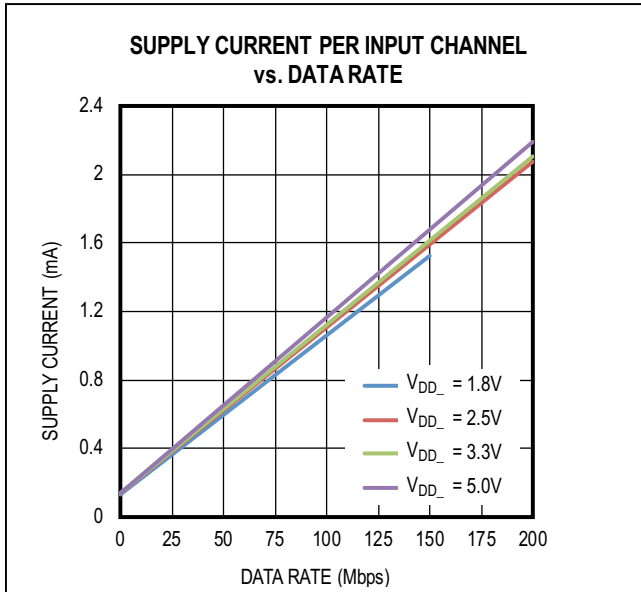


Figure 7. Supply Current Per Input Channel

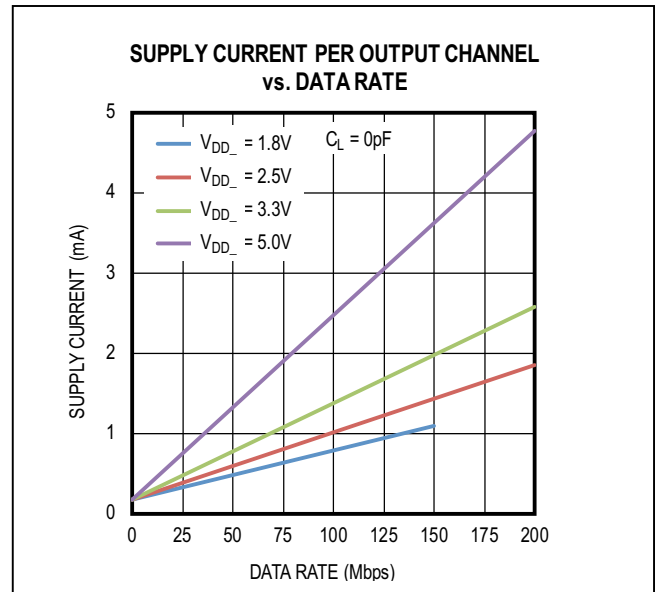


Figure 8. Supply Current Per Output Channel

Table 5. Side A Supply Current Calculation Worksheet

| SIDE A | | V _{DDA} = 3.3V | | | | |
|---------------------|--------|-------------------------|------------|------|------------------------|---|
| Channel | IN/OUT | Data Rate (Mbps) | Load Type | Load | “No Load” Current (mA) | Load Current (mA) |
| O AUX | OUT | 1 | Capacitive | 10pF | 0.19 | $3.3V \times 0.5MHz \times 10pF = 0.017$ |
| O SDI | OUT | 10 | Capacitive | 15pF | 0.30 | $3.3V \times 5MHz \times 15pF = 0.25$ |
| O SCLK | OUT | 20 | Capacitive | 15pF | 0.42 | $3.3V \times 10MHz \times 15pF = 0.50$ |
| \overline{OCS} | OUT | 2.5 | Capacitive | 15pF | 0.21 | $3.3V \times 1.25MHz \times 15pF = 0.062$ |
| I SDO | IN | 10 | | | 0.24 | |
| \overline{IFAULT} | IN | 0 | | | 0.14 | |
| Total: 2.33mA | | | | | | |

Table 6. Side B Supply Current Calculation Worksheet

| SIDE B | | V _{ddb} = 2.5V | | | | |
|---------------------|--------|-------------------------|------------|------|------------------------|---------------------------------------|
| Channel | IN/OUT | Data Rate (Mbps) | Load Type | Load | “No Load” Current (mA) | Load Current (mA) |
| I AUX | IN | 1 | | | 0.15 | |
| I SDI | IN | 10 | | | 0.23 | |
| I SCLK | IN | 20 | | | 0.33 | |
| \overline{ICS} | IN | 2.5 | | | 0.16 | |
| O SDO | OUT | 10 | Capacitive | 15pF | 0.27 | $2.5V \times 5MHz \times 15pF = 0.19$ |
| \overline{OFAULT} | OUT | 0 | Resistive | 10kΩ | 0.18 | $2.5V \div 10k\Omega = 0.25$ |
| Total: 1.76mA | | | | | | |

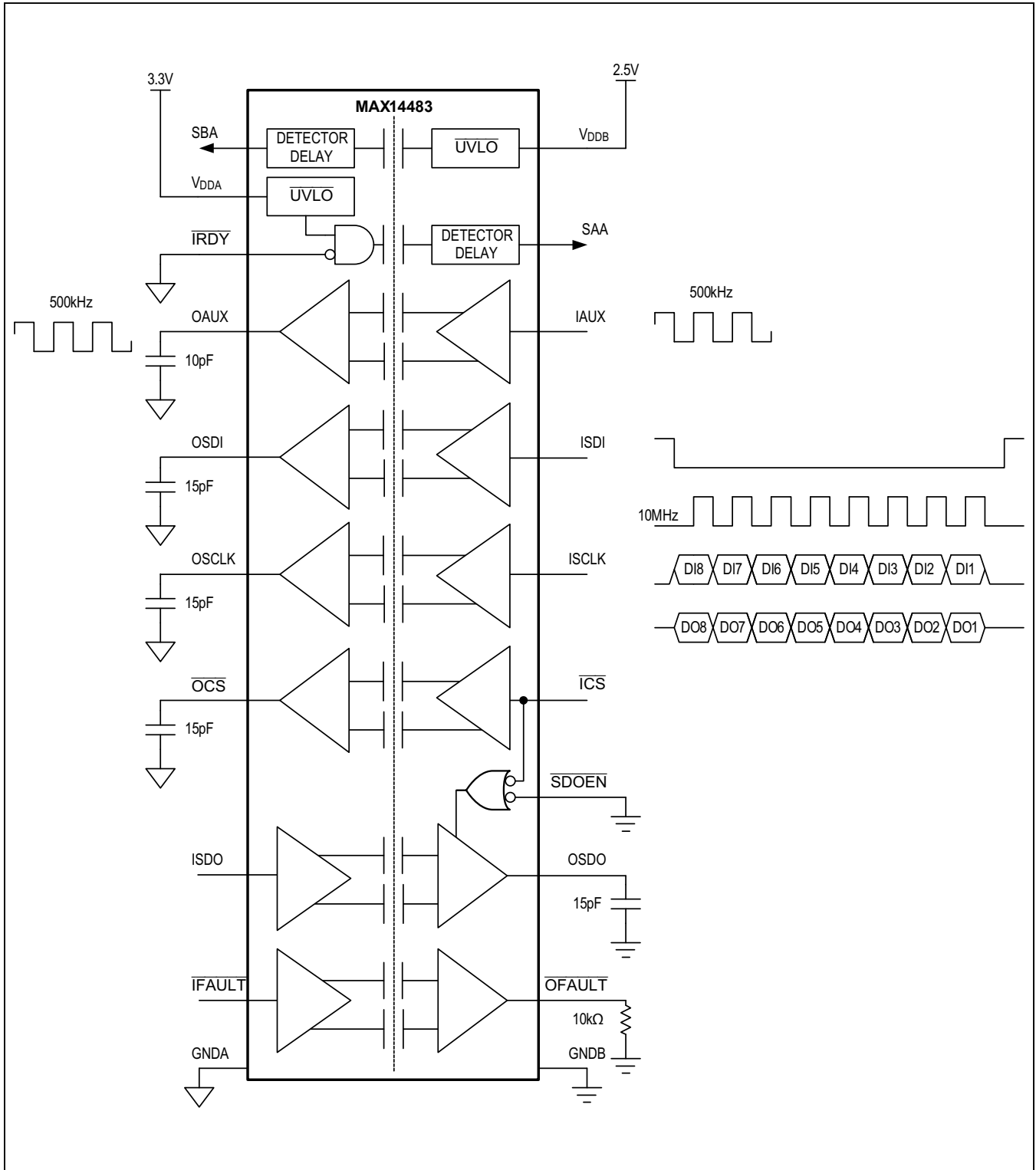
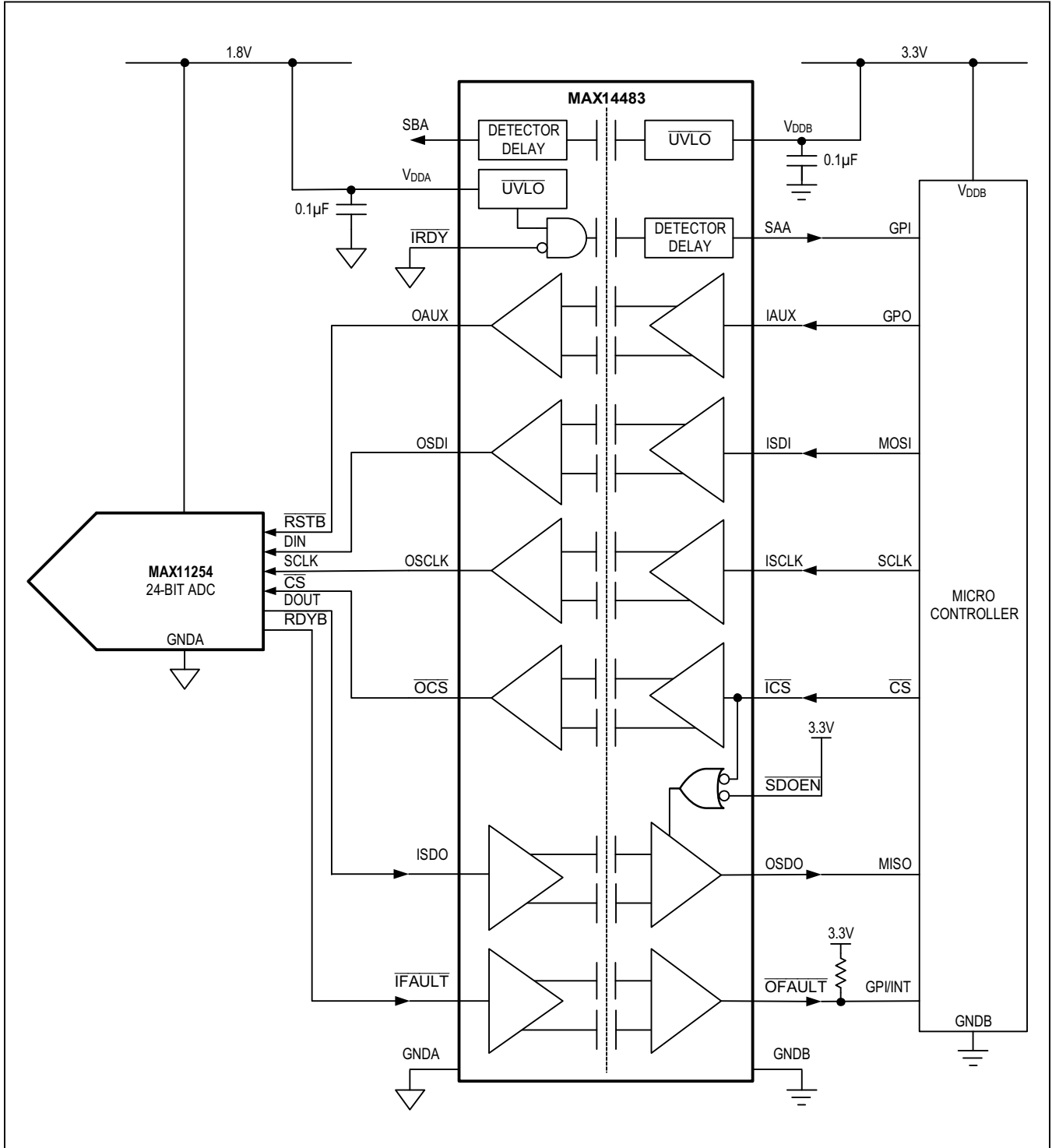
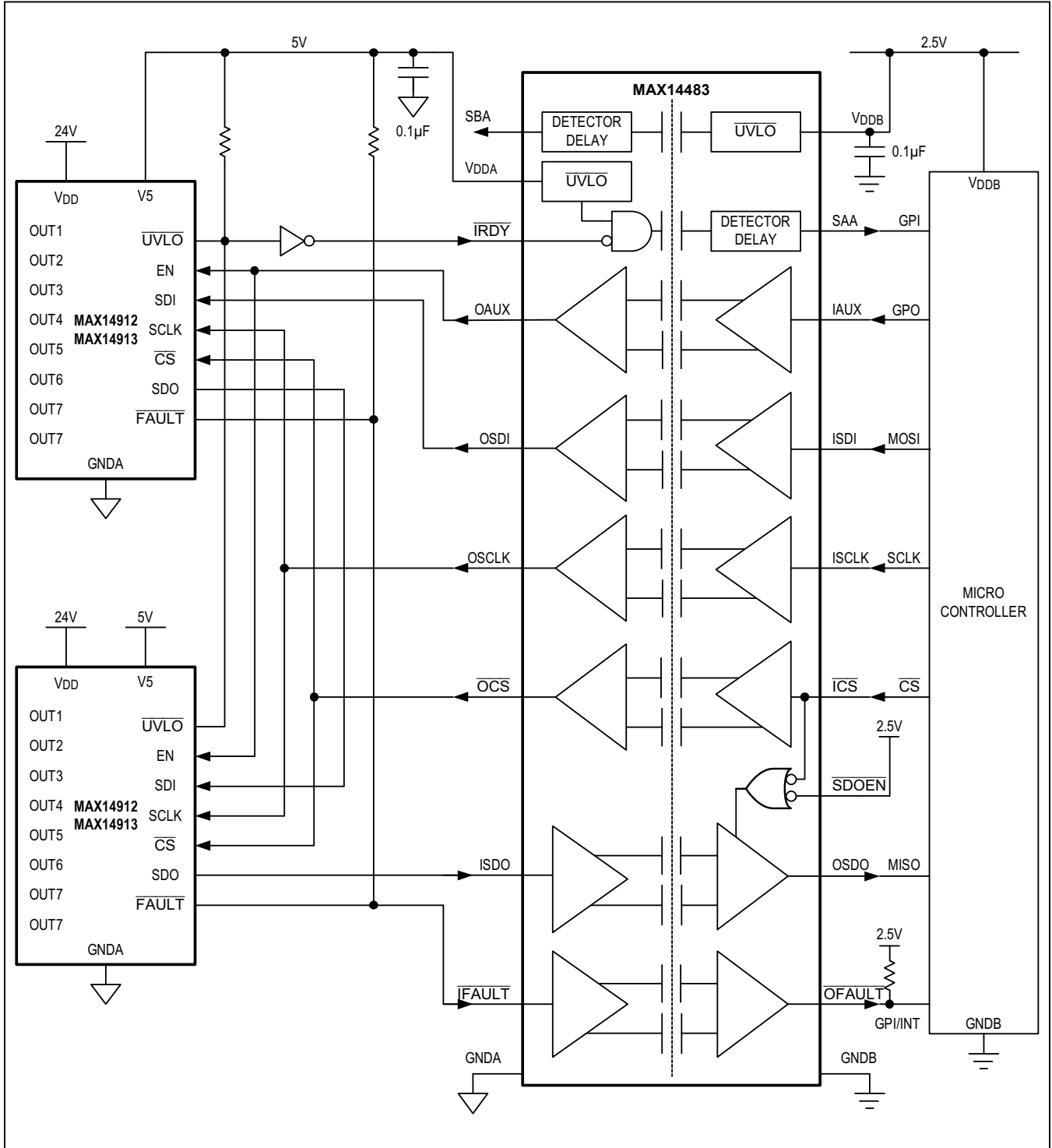


Figure 9. Example Circuit for Supply Current Calculation

Typical Operating Circuit
Isolated SPI Interface

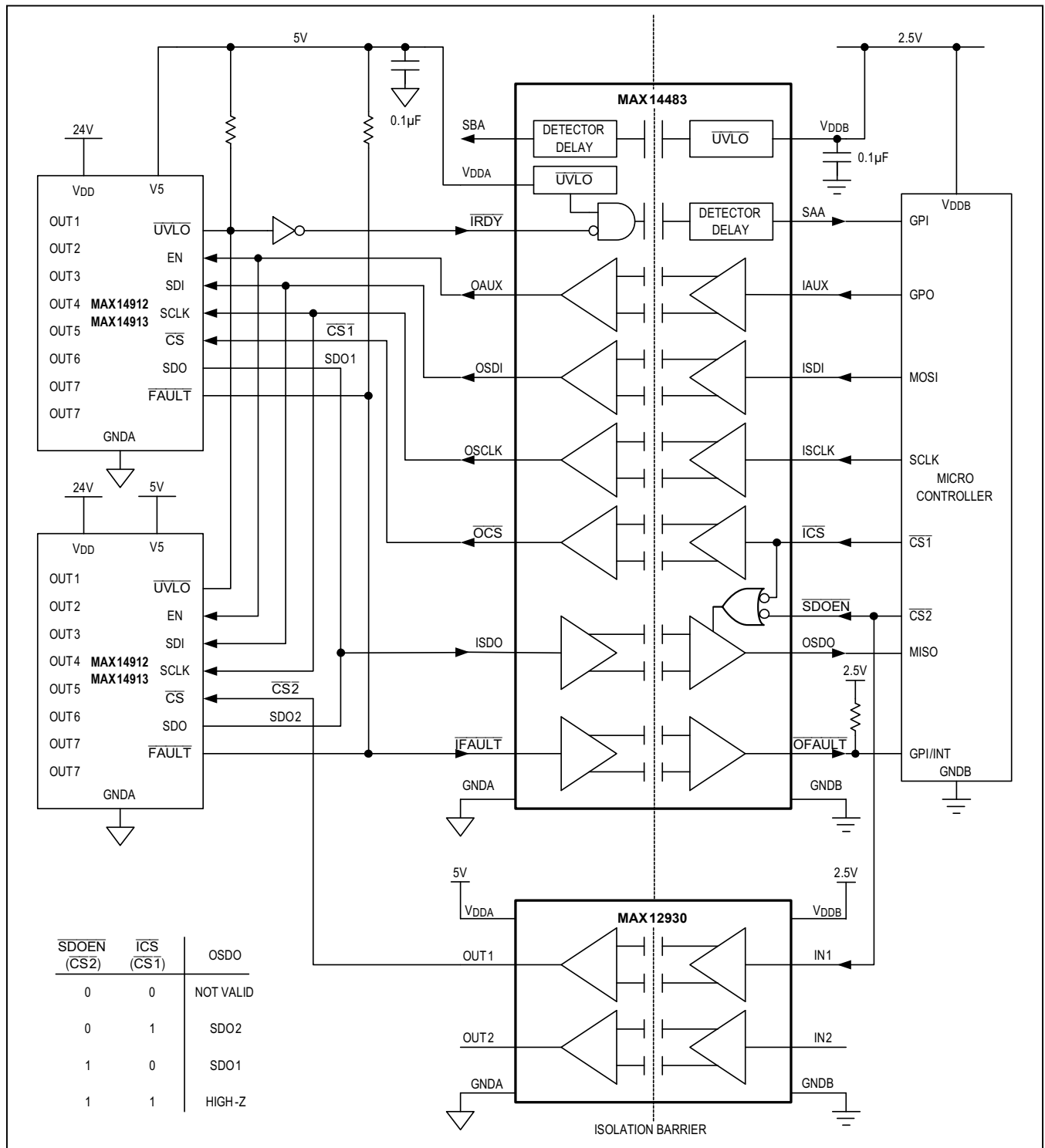


Typical Operating Circuit (continued)
Isolated SPI Daisy Chain, 16 Digital Outputs



Typical Operating Circuit (continued)

Isolated Independent Slave SPI Bus, 16 Digital Outputs



MAX14483

6-Channel, Low-Power,
3.75kVRMS, SPI Digital Isolator

Ordering Information

| PART | ISOLATION VOLTAGE (KVRMS) | TEMP RANGE (°C) | PIN-PACKAGE |
|--------------|------------------------------|--------------------|-------------|
| MAX14483AAP+ | 3.75 | -40 to +125 | 20-SSOP |

Chip Information

PROCESS: BiCMOS

Package Information

For the latest package outline information and land patterns (footprints), go to www.maximintegrated.com/packages. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

| PACKAGE TYPE | PACKAGE CODE | OUTLINE NO. | LAND PATTERN NO. |
|--------------|--------------|-------------------------|-------------------------|
| 20 SSOP | A20MS+7 | 21-0056 | 90-0094 |

Revision History

| REVISION NUMBER | REVISION DATE | DESCRIPTION | PAGES CHANGED |
|-----------------|---------------|---|---------------|
| 0 | 08/17 | Initial release | — |
| 1 | 2/18 | Updated <i>Electrical Characteristics</i> table, <i>Typical Operating Characteristics</i> , and <i>Detailed Description</i> section | 1–20 |

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim Integrated's website at www.maximintegrated.com.

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